

# AMPL SOLVER INTERFACES WITH CALLBACKS

FEATURING: PYTHON CALLBACKS FOR GUROBI AND CPLEX!

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# What is AMPL?



- AMPL: **A Mathematical Programming Language**
- Algebraic modeling language built specially for optimization
- Designed to support many solvers
- Natural, easy-to-learn modeling principles
- Efficient processing that scales well with problem size

# Model: diet.mod

*# Choose prepared foods to meet certain nutritional requirements:*

```
set NUTR;
```

```
set FOOD;
```

```
param cost {FOOD} > 0;
```

```
param f_min {FOOD} >= 0;
```

```
param f_max {j in FOOD} >= f_min[j];
```

```
param n_min {NUTR} >= 0;
```

```
param n_max {i in NUTR} >= n_min[i];
```

```
param amt {NUTR,FOOD} >= 0;
```

```
var Buy {j in FOOD} >= f_min[j], <= f_max[j];
```

```
minimize Total_Cost: sum {j in FOOD} cost[j] * Buy[j];
```

```
subject to Diet {i in NUTR}:
```

```
    n_min[i] <= sum {j in FOOD} amt[i,j] * Buy[j] <= n_max[i];
```

# How to interact with the model and the data?

## Using the Python API (amplpy):

```
>>> from amplpy import AMPL
>>> ampl = AMPL()                               # > ampl
>>> ampl.read('diet.mod')                       # ampl: model diet.mod;
>>> ampl.read('diet.dat')                      # ampl: data diet.dat;
>>> ampl.option['solver'] = 'gurobi'          # ampl: option solver gurobi;
>>> ampl.solve()                               # ampl: solve;
```

Gurobi 7.5.0: optimal solution; objective 88.2

1 simplex iterations

```
>>> ampl.getVariable('Buy').getValues().toPandas()
```

	Buy.val
BEEF	0.000000
CHK	0.000000
FISH	0.000000
HAM	0.000000
MCH	46.666667
MTL	0.000000
SPG	0.000000
TUR	0.000000

# Setting data from Python

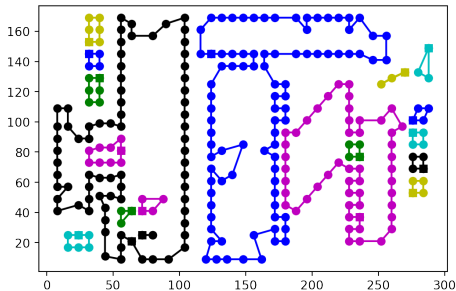
## In Python:

```
>>> ampl.set['FOOD'] = [  
    'BEEF', 'CHK', 'FISH', 'HAM', 'MCH', 'MTL', 'SPG', 'TUR']  
>>> ampl.param['cost'] = [  
    3.59, 2.59, 2.29, 2.89, 1.89, 1.99, 1.99, 2.49]  
>>> ampl.param['f_min'] = [2, 2, 2, 2, 2, 2, 2, 2]  
>>> ampl.param['f_max'] = [10, 10, 10, 10, 10, 10, 10, 10]  
>>> ampl.eval('display cost, f_min, f_max;')  
:  
cost f_min f_max :=  
BEEF 3.59 2 10  
CHK 2.59 2 10  
FISH 2.29 2 10  
HAM 2.89 2 10  
MCH 1.89 2 10  
MTL 1.99 2 10  
SPG 1.99 2 10  
TUR 2.49 2 10  
;
```

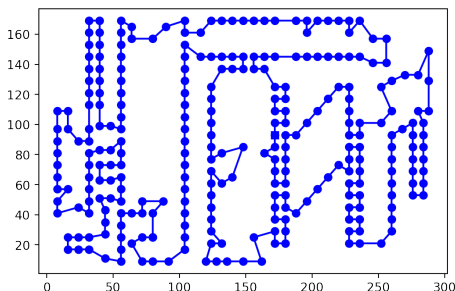
# Travelling Salesman Problem (TSP)

"Given a list of cities and the distances between each pair of cities, what is the shortest possible route that visits each city exactly once and returns to the origin city?"

Invalid solution with sub-tours:



Optimal solution without sub-tours:



TSP instance: a280.tsp from TSPLIB.

# Travelling Salesman Problem (TSP)

```
from amplpy import AMPL
ampl = AMPL()
ampl.eval('''
param n;
set V := 1..n;
set A := {(i,j) in V cross V : i != j};
param c{A} >= 0 default Infinity;
var x{A}, binary;
minimize Tour_Length: sum{(i,j) in A} c[i,j] * x[i,j];
s.t. enter{j in V}: sum{i in V: i != j} x[i, j] == 1;
s.t. leave{i in V}: sum{j in V: j != i} x[i, j] == 1;

# subtour elimination Miller, Tucker and Zemlin (MTZ) (1960)
var u{V} >= 0;
subject to MTZ{(i,j) in A: i != 1}: u[i]-u[j] + (n-1)*x[i,j] <= n-2;
''')
n, dist = load_tsp_instance('instance.txt')
ampl.param['n'] = n
ampl.param['c'] = dist
```

# Travelling Salesman Problem (TSP)

What happens if you try to solve a280.tsp with just 280 nodes without callbacks using just MTZ constraints:

Root relaxation: objective 2.431206e+03, 579 iterations, 0.28 seconds

Nodes		Current Node			Objective Bounds			Work	
Expl	Unexpl	Obj	Depth	IntInf	Incumbent	BestBd	Gap	It/Node	Time
0	0	2431.20637	0	447	-	2431.20637	-	-	2s
0	0	2515.52499	0	525	-	2515.52499	-	-	11s
0	0	2515.52499	0	526	-	2515.52499	-	-	36s
0	0	2531.19773	0	496	-	2531.19773	-	-	38s
0	0	2534.89984	0	510	-	2534.89984	-	-	38s
0	0	2534.89984	0	510	-	2534.89984	-	-	38s
0	0	2541.20314	0	496	-	2541.20314	-	-	40s
0	0	2541.20314	0	496	-	2541.20314	-	-	89s
0	0	2541.20314	0	496	-	2541.20314	-	-	91s
0	0	2541.22366	0	501	-	2541.22366	-	-	109s
0	0	2541.22366	0	501	-	2541.22366	-	-	109s
0	0	2541.22366	0	385	-	2541.22366	-	-	112s
0	0	2541.22366	0	385	-	2541.22366	-	-	112s
0	0	2541.22366	0	378	-	2541.22366	-	-	114s
0	0	2541.22366	0	378	-	2541.22366	-	-	114s
0	0	2541.22366	0	376	-	2541.22366	-	-	117s
0	0	2541.22366	0	375	-	2541.22366	-	-	258s
0	0	2541.22366	0	447	-	2541.22366	-	-	260s



# Defining a simple generic callback in Python

This is a very simple callback that just provides additional information to the user.

```
import amplpy_gurobi as ampls
# Define my generic callback function
class MyCallback(ampls.GenericCallback):
    def __init__(self):
        self.nMIPnodes = 0
    def run(self):
        t = self.getAMPLWhere()
        if t == ampls.Where.MSG:
            print('>' + self.getMessage())
        elif t == ampls.Where.MIPNODE:
            self.nMIPnodes += 1
            print("New MIP node, count {}".format(self.nMIPnodes))
        elif t == ampls.Where.MIPSOL:
            print("MIP Solution = {}".format(self.getObj()))
        return 0
```

# Using the callback with Gurobi

## Export model object, optimize, and import solution:

```
m = ampl.exportModel('gurobi') # export model object
cb = MyCallback()              # instantiate callback
m.setCallback(cb)              # set the callback to use
m.optimize()                    # run the optimization process
if m.getStatus() == ampl.Status.OPTIMAL:
    ampl.importSolution(m)      # load the solution into ampl
    ampl.display('Tour_Length') # display objective value form ampl
```

## Output of m.optimize():

```
...
MIP Solution = 460.07905777356814
>* 206 208 44 460.0790578 419.71967 8.77% 19.5 1s
MIP Solution = 440.442642507044
>H 230 206 440.4426425 419.75510 4.70% 18.6 1s
MIP Solution = 439.9556742664898
>* 354 250 42 439.9556743 419.75510 4.59% 18.3 1s
MIP Solution = 439.1123891294378
>* 490 284 55 439.1123891 420.06206 4.34% 18.1 1s
MIP Solution = 436.18563128541143
>H 1046 627 436.1856313 423.97345 2.80% 18.0 3s
> 1074 648 426.46288 12 128 436.18563 426.46288 2.23% 19.9 5s
MIP Solution = 435.47746822093836
>H 1082 619 435.4774682 426.47191 2.07% 19.7 5s
MIP Solution = 432.502179738009
>H 1089 593 432.5021797 426.47191 1.39% 22.3 6s
MIP Solution = 431.10323765840644
>H 1191 621 431.1032377 426.75789 1.01% 24.6 8s
MIP Solution = 428.871756392034
>* 1567 655 120 428.8717564 426.75789 0.49% 23.4 8s
...
```

# Symmetric Traveling Salesman Problem

```
set NODES ordered;  
param hpos {NODES};  
param vpos {NODES};  
  
set PAIRS := {i in NODES, j in NODES: ord(i) < ord(j)};  
  
param distance {(i,j) in PAIRS}  
    := sqrt((hpos[j]-hpos[i])**2 + (vpos[j]-vpos[i])**2);  
  
var X {PAIRS} binary;  
  
minimize Tour_Length: sum {(i,j) in PAIRS} distance[i,j] * X[i,j];  
  
subject to Visit_All {i in NODES}:  
    sum {(i, j) in PAIRS} X[i,j] + sum {(j, i) in PAIRS} X[j,i] = 2;
```

# Generate sub-tour elimination cuts with a callback

```
import amply_cplex as ampls # use cplex instead of gurobi
class TSPCuts(ampls.GenericCallback):
    def run(self):
        if self.getAMPLWhere() == ampls.Where.MIPSOL:
            self.mipsol()
        return 0
    def mipsol(self):
        sol = self.getSolutionVector()
        uf = UnionFind()
        for i, (u, v) in xvars.items():
            if sol[i] > 1e-5:
                uf.link(u, v)
        groups = uf.groups()
        if len(groups) == 1:
            print('Valid solution!')
            return
        for g in groups:
            print('> sub-tour: ', g)
            vnames = [tuple2var('X', i, j) for i in g for j in g if i < j]
            coeffs = [1 for i in range(len(vnames))]
            self.addLazy(vnames, coeffs, ampls.CutDirection.LE, len(grp)-1)
```

# Using the callback with CPLEX

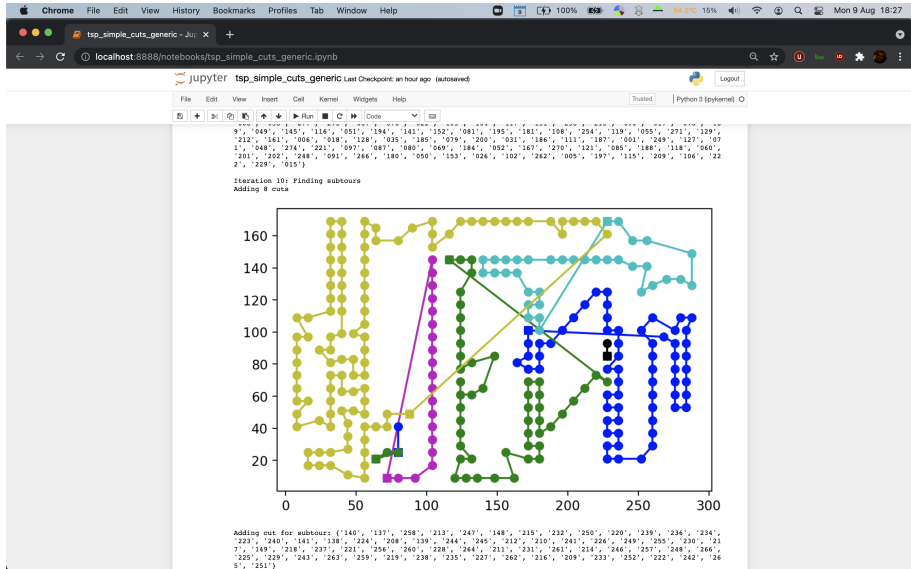
## Export model object, optimize, and import solution:

```
m = ampl.exportModel('cplex'). # export model object
m.enableLazyConstraints(). # enable lazy constraints
cb = TSPCuts() # instantiate callback
m.setCallback(cb) # set the callback to use
m.optimize() # run the optimization process
if m.getStatus() == ampl.Status.OPTIMAL:
    ampl.importSolution(m) # load the solution into ampl
    ampl.display('Tour_Length') # display objective value form ampl
```

## Output of m.optimize():

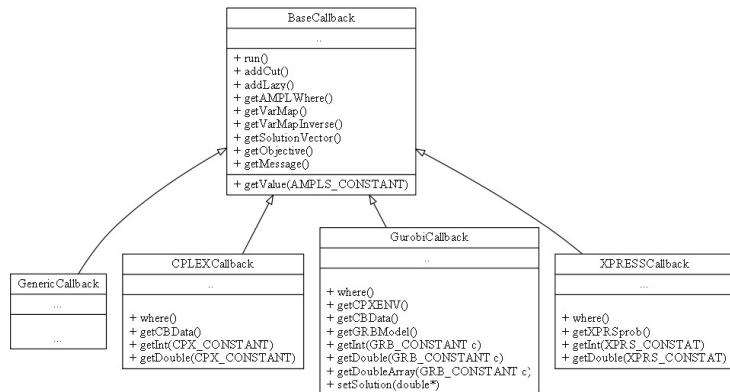
```
...
MIPSOL #16
Valid solution!
MIPSOL #17
> sub-tour: ['1', '6', '3', '29', '4', '47', '5', '35', '7', '37', '8', '20', '9', '10', '46', '11', '12', '19', '13', '14']
> sub-tour: ['2', '32']
> sub-tour: ['21', '26', '38']
> sub-tour: ['22', '44']
> sub-tour: ['30', '43']
MIPSOL #18
> sub-tour: ['1', '34', '2', '32', '3', '6', '4', '28', '5', '9', '7', '37', '8', '14', '47', '10', '11', '29', '12', '13', '14']
> sub-tour: ['25', '42']
MIPSOL #19
> sub-tour: ['1', '34', '3', '29', '4', '47', '5', '35', '6', '7', '37', '8', '20', '9', '10', '46', '11', '13', '31', '32']
> sub-tour: ['2', '26', '21']
> sub-tour: ['12', '43', '22', '38', '30', '44']
> sub-tour: ['23', '32']
MIPSOL #20
Valid solution!
```

# Jupyter Notebook



# Conclusions 1/2

- Even though this presentation was focused on callbacks in Python, we provide solver extensions with callbacks for other languages and solvers.
- We provide a generic interface that allows implementing callbacks that work seamlessly with multiple solvers, and solver specific interfaces so that users can take full advantage of everything a specific solver provides.



## Conclusions 2/2

- The solver libraries for Gurobi and CPLEX can be installed as easily as:

```
python -m pip install amplpy_gurobi
python -m pip install amplpy_cplex
```
- Last but not least, all these interfaces are **open-source** so that users can contribute to them and extend them to support additional languages and solver features.
- GitHub project: <https://github.com/ampl/ampls-api>
- Documentation for solver libraries: <https://ampls.readthedocs.io>
- Documentation for amplpy: <https://amplpy.readthedocs.io>